GENERAL ORDER 22

EFFECTIVE: 1 October 1996

REVISED: 1 August 2000

1 January 2010 20 June 2011 21 April 2016

SUBJECT: Traffic Enforcement/Radamd LIDAR

ISSUED BY: Fernando Solorzano

I. PURPOSE

To establish guidelines for the use of the Department's radar units and Lidar handheld for the enforcement of speeding violations.

II. POLICY

It is the policy of this Department to create a safe environment for all students, faculty, staff and visitors. To assist in the reduction of motor vehicle accidents and to help ensure that all vehicles and pedestrians move safety across the campus and surrounding tices sof

speedometer with speed indicated to adar in the moving mode. This test should be conducted at 25, 35 and 45 mph or 25, 30 and 40 mph, depending on the configuration of the speedometer.

(b) LIDAR CALIBRATION

- (1) PowerOn SelfTest When the Lidar is powered on, a complete **test**-is completed and the words "PASS" will display if it is functioning properly. If the selftest fails the unit will be taken out of service and returned to *Stalker Inc.*
- (2) Manual SelfTest The Officer will run a selftest prior each day when the Lidar is deployed in the field and prior to enforcement. If the unit does not display "PASS" the unit must be turned off for the Po@erSelfTest. If the Self-Test shows "PASS" the Manual Selfest will attempted again.
- (3) Sight Alignment Test- The sight Alignment test should be conducted each shift prior to enforcement and at the end of the shift to ensure the units aim was accurate throughout the shift.
- (c) DOCUMEN(a)-1yC /LI Tw 0.N(a)-1yC /t Tes

weigh all circumstance รง่งolved when determining a proper course of action. However, the following are established as Department guidelines for the citing of speeding violations. These are only guidelines and are not intended to be absolutes:

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